IN THE CLAIMS:

- (Currently Amended) A drive unit, preferably an actuator comprising a DC motor having a rotor consisting of a plurality of coils connected to a commutator in connection with a set of brushes to establish a voltage across the coils, said DC motor, via a transmission, driving an adjustment means for adjusting an adjustable element in a structure in which the drive unit is incorporated, said drive unit being supplied with power from a power supply comprising a transformer having a primary side for connection to a mains voltage (alternating current) and a secondary side with rectification and smoothing for connection to the DC motor, characterized in that it comprises a first control to compensate for the loss in the motor, thereby keeping the a speed thereof constant for a long-first period of time, as well as second control adapted to remove the that removes ripple in the voltage, thereby keeping the speed of the motor constant for a short second period of time, said second period of time being shorter in duration than said first period of time.
- 2. (Currently Amended) A drive unit according to claim 1, characterized in that wherein the second control is performed by the following two steps, via. comprises:
- a forward step in which the \underline{a} duty cycle \underline{may} be \underline{is} expressed by k and V_{in} , and
- a power step in which V_{out} $\frac{\text{may be-}\text{is}}{\text{expressed}}$ by V_{in} and the duty cycle,

a power step in which V_{out} may be is expressed by V_{in} and the duty cycle, wherein the result of the forward step and the power step is $V_{out} = K$, and wherein V_{in} is the an input voltage from the rectification, V_{out} is the an output voltage from the power step, k is a constant given by the actual circuits for the forward step and the power step, and wherein the duty step is the proportional time for which the power supply may be is loaded during a given period of time.

- 3. (Currently Amended) A power-supply drive unit according to claim 2, characterized in that wherein the forward step is given by: duty cycle = k/V_{in} , and the power step by: $V_{out} = V_{in}$. duty cycle $V_{out} = V_{in} * duty$ cycle.
- 4. (Currently Amended) A power supply drive unit according to claim 2, characterized in that wherein the forward step is given by: duty cycle = V_{in}/k , and the power step by: $V_{out} = V_{in}/duty$ cycle.
- 5. (Currently Amended) A control unit for units, including actuators comprising a DC motor which, via a transmission, drives an adjustment means for adjusting an adjustable element in a structure in which the drive unit is incorporated, said drive unit being supplied with power from a power supply comprising a transformer having a primary side for connection to a mains voltage and a secondary side with rectification and

smoothing for connection to the DC motor, characterized in that wherein the control unit comprises a first control to compensate for the loss in the motor, thereby keeping the a speed thereof constant for a long-first period of time, as well as a second control adapted to remove the for removing ripple in the voltage, thereby keeping the sped of the motor constant for a short second period of time, said second period of time being shorter in duration than said first period of time.

6. (Currently Amended) A structure, in particular an article of furniture having at least an element which may be that is adjusted with at least a DC motor, preferably via a mechanical transmission, and DC motor being connected to a power supply comprising a transformer having a primary side for connection to a mains voltage and a secondary side with rectification and smoothing for connection to the DC motor, characterized in that wherein the secondary side of the power supply is additionally provided with a first control to compensate for the loss in the motor, thereby keeping the a speed thereof constant for a long-first period of time, as well as with a second control adapted to remove the for removing ripple in the voltage, thereby keeping the speed of the motor constant for a short second period of time, said second period of time being shorter in duration than said first period of time.

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7. (New) A drive unit according to claim 1, wherein said first period of time is 30 msec. to 1 sec. and said second period of time is less than 10 msec.